# Message-Passing and MPI Programming More on Datatypes and Collectives

N.M. Maclaren

nmm1@cam.ac.uk

July 2010

# 5.1 Introduction

There are a few important facilities we have not covered yet; they are less commonly used, but are fairly often needed. In particular, one of them can help a lot with I/O.

There is also some information on how to use collectives efficiently, including one potentially useful minor feature.

# 5.2 Fortran Selectable Precisions

This topic is relevant only to Fortran 90 programmers, but it is almost trivial to use and very useful for portability. Fortran 90 allows selectable precisions, using the intrinsics SELECTED\_INTEGER\_KIND and SELECTED\_REAL\_KIND. The following is just a summary and example, but that is all you will need to use the facility; as a reminder, those intrinsics select a suitable KIND value and use the syntax:

```
KIND=SELECTED_INTEGER_KIND(precision)
KIND=SELECTED_REAL_KIND(precision[,range])
```

You can create a MPI derived datatype to match these, and then use it just like a built-in datatype; the MPI functions match the intrinsics very closely. All you have to do is to call the datatype constructor and then use it like a built-in MPI type. Surprisingly, it is a predetermined type, and you must neither commit nor free it, though this sentence will make sense only if you learn more about MPI derived types; just ignore it until you do. For example:

```
INTEGER ( KIND = SELECTED_INTEGER_KIND ( 15 ) ) , &
DIMENSION ( 100 ) :: array
INTEGER :: root , integertype , error
CALL MPI_Type_create_f90_integer ( 15 , integertype , error )
CALL MPI_Bcast ( array , 100 , integertype , root , &
MPI_COMM_WORLD , error )
REAL and COMPLEX are very similar:
```

```
REAL ( KIND = SELECTED_REAL_KIND ( 15 , 300 ) ) , &
DIMENSION ( 100 ) :: array
CALL MPI_Type_create_f90_real ( 15 , 300 , realtype , error )
COMPLEX ( KIND = SELECTED_REAL_KIND ( 15 , 300 ) ) , &
```

```
DIMENSION ( 100 ) :: array
CALL MPI_Type_create_f90_complex ( &
15 , 300 , complextype , error )
```

#### 5.3 Searching

You can use global reductions for searching. The bad news is that it needs MPI's derived datatypes, but the good news is that there are some useful built-in ones. All we need to do is a reduction with a composite datatype (<value>,<index>). As with summation, we build up the reduction from a binary operator, and there are two built-in operators, MPI\_MINLOC and MPI\_MAXLOC. We shall use finding the minimum as an example.

We start with two values, (value\_1,index\_1) and (value\_2,index\_2), and produce a result(value\_x,index\_x). The algorithm for the binary operator is simply:

```
\begin{array}{l} \mbox{If value_1} \leq \mbox{value_2} \mbox{ then } \\ \mbox{value_x} \ll \mbox{value_1} \\ \mbox{index_x} \leftarrow \mbox{index_1} \\ \mbox{Else} \\ \mbox{value_x} \leftarrow \mbox{value_2} \\ \mbox{index_x} \leftarrow \mbox{index_2} \end{array}
```

Equality is a bit cleverer, but it rarely matters; if it does matter to your program, see the MPI standard for the detailed specification. Operator MPI\_MINLOC does precisely what we have described; operator MPI\_MAXLOC searches for the maximum, and is the same with  $\leq$  replaced by  $\geq$ .

Note that you create the (value, index) pairs first, and the the index can be anything, so set it to whatever is useful for your program. Generally, an index should usually be globally unique (i.e. not just the index into a local array). For example, you can combine the process number and a local index. So how do we set up the data?

## 5.4 Fortran Searching

Fortran 77 did not have derived types (structures), though Fortran 90 does, so the datatypes are arrays of length two. The ones to use are MPI\_2INTEGER and MPI\_2DOUBLE\_PRECISION. Note that DOUBLE PRECISION can hold any INTEGER value, on any current MPI system; in fact, it is almost required by the Fortran standard, and so is a safe assumption in almost all programs. MPI\_2REAL is not recommended, except on *Cray* vector systems.

Using these for searching is very simple, as in the following example:

```
INTEGER :: sendbuf ( 2 , 100 ) , &
    recvbuf ( 2 , 100 ) , myrank , error , i
INTEGER, PARAMETER :: root = 3
CALL MPI_Comm_rank ( MPI_COMM_WORLD , myrank , error )
DO i = 1 , 100
sendbuf ( 1 , i ) = <value>
sendbuf ( 2 , i ) = 1000 * myrank + i
END DO
CALL MPI_Reduce ( sendbuf , recvbuf , 100, MPI_2INTEGER , &
    MPI_MINLOC , root , MPI_COMM_WORLD , error )
```

## 5.5 C Searching

C has always had structures, so the datatypes are "struct {<value type>; int;}". Unfortunately, C structure layout is a can of worms, so certain compiler options may cause trouble. What is described here will usually work; if it does not, you will need to ask for help from an expert on both C and your compiler. Most probably, you will never encounter the problems if you follow these rules.

The recommended datatypes are MPI\_2INT, MPI\_LONG\_INT and MPI\_DOUBLE\_INT, corresponding to <value type>s of int, long and double. You can also use MPI\_LONG\_DOUBLE\_INT for "long double", if you use that. Do not use MPI\_FLOAT\_INT or SHORT\_INT for C reasons you do not want to know!

 $\mathbf{C}$ :

```
struct { double value ; int index ; }
    sendbuf [100] , recvbuf [100] ;
int root = 3, myrank , error , i;
for ( i = 1 ; i < 100 ; ++i ) {
    sendbuf [ i ] . value = <value> ;
    sendbuf [ i ] . index = 1000 * myrank + i ;
}
error = MPI_Reduce ( sendbuf , recvbuf ,
    100, MPI_DOUBLE_INT , MPI_MINLOC ,
    root , MPI_COMM_WORLD )
```

## 5.6 Data Distribution

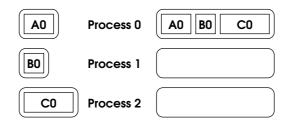
It can be inconvenient to make all counts the same, such as with a 100×100 matrix on 16 CPUs. One approach is to pad the short vectors, and that is usually more efficient than it looks. There are also extended MPI collectives for handling non-identical counts (MPI\_Gatherv, MPI\_Scatterv, MPI\_Allgatherv and MPI\_Alltoallv) but, obviously, their interface is more complicated. You should use whichever approach is easiest for you.

The count argument is now a vector of counts instead of a single count, with one count for each process, but only where there are multiple buffers. That is the receive counts for MPI\_Gatherv and MPI\_Allgatherv, the send counts for MPI\_Scatterv and both counts for MPI\_Alltoallv. It is used only on the root process for MPI\_Gatherv and MPI\_Scatterv. For MPI\_Allgatherv, the count vectors must match on all processes. MPI\_Alltoallv is described in a moment. The most reliable approach is always to make them match, for sanity; if you then change the root process, nothing will break.

The scalar counts may all be different, of course, because they must match for each pairwise send and receive. For example:

• For MPI\_Gatherv, the send count on process N matches the Nth receive count element on the root. MPI\_Scatterv just the converse of MPI\_Gatherv.

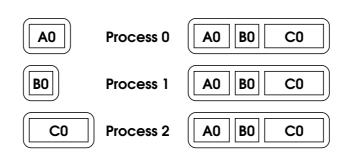
#### Gatherv





• For MPI\_Allgatherv, the send count on process N matches Nth receive count element on all processes.

# Allgatherv



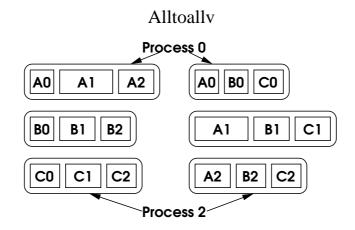


The most complicated one is MPI\_Alltoallv, though it is not hard to use, if you keep a clear head. You should use a pencil and paper if you get confused, which is a good general

rule for programming. Consider processes M and N:

• For MPI\_Alltoallv, the Nth send count on process M matches the Mth receive count on process N.

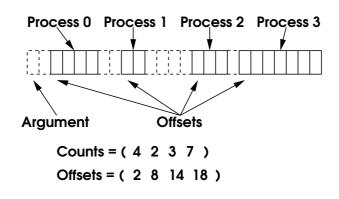
As was said earlier, think of it as a matrix transpose with the data vectors as its elements.





Where they have a vector of counts, they also have a vector of offsets. This is the offset of the sub-vector of data corresponding to each process, and **not** the offset of the basic elements. This allows for discontiguous buffers, but each pairwise transfer must still be contiguous. Normally, the first offset will be zero, But here is a picture of when it is not:

### Multiple Transfer Buffers



#### Figure 5.4

Unlike the counts, the offsets are purely local, and they need not match on all processes; even in the case of MPI\_Alltoallv, the offset vectors need not match in any way. Each one is used just as a mapping for the local layout of its associated buffer.

Keep your use of these collectives simple; MPI will not get confused, but you and I will, and remember that any overlap is undefined behaviour. The following picture of a

fairly general MPI\_Alltoallv is just to see what can be done, and not to recommend such practice:

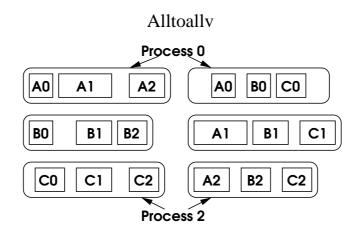


Figure 5.5

The examples are simple ones of using MPI\_Gatherv; you should start with either this or MPI\_Scatterv when testing.

#### Fortran:

 $\mathbf{C}$ :

```
INTEGER, DIMENSION (0 : *) :: counts
REAL(KIND=KIND(0.0D0)) ::
                            &
    sendbuf (100), recvbuf (100, 30)
INTEGER :: myrank , error, i
INTEGER , PARAMETER :: root = 3 ,
                                    &
    offsets ( * ) = (/ ( 100 * i , i = 0 , 30 - 1 ) /)
CALL MPI_Gatherv (
                     &
    sendbuf , counts ( myrank ) , MPI_DOUBLE_PRECISION ,
                                                           &
    recvbuf , counts , offsets , MPI_DOUBLE_PRECISION ,
                                                           &
    root , MPI_COMM_WORLD , error )
int counts [];
double sendbuf[100] , recvbuf[30][100] ;
int root = 3 , offsets[30] , error, i ;
for (i = 0; i < 30; ++ i)
    offsets [ i ] = 100 * i ;
error = MPI_Gatherv (
    sendbuf , counts [ myrank ] , MPI_DOUBLE ,
    recvbuf , counts , offsets , MPI_DOUBLE ,
    root , MPI_COMM_WORLD ) ;
```

Using these functions is fairly easy when the counts are predictable, but a lot of the time, they will not be. The easiest way to solve that problem is:

- For scatter, calculate the counts on the root process, use MPI\_Scatter to distribute the count values, and then do the full MPI\_Scatterv on the data.
- For gather, calculate a count on each process, use MPI\_Gather to collect the count values, and then do the full MPI\_Gatherv on the data.

## 5.7 Efficiency

Generally, you should use collectives whereever possible, because they provide most opportunity for the implementation to tune the calls. Similarly, you should use the composite ones (MPI\_Allgather, MPI\_Allreduce and MPI\_Alltoall) where that makes sense, just as you should use the level 3 *BLAS* (DGEMM etc.) in preference to the level 2 ones (DGEMV etc.)

You should also do as much as possible in one collective – fewer, larger transfers are always better than a lot of small ones. Consider packing scalars into arrays for copying, even converting integers to reals (double precision, please!) to do so. It is not worth packing multiple large arrays into one, and a good rule of thumb is that the boundary between 'small' and 'large' is a single, pairwise transfer buffer of about 4 KB. But remember that it is only a rule of thumb, and do not waste time packing data unless you actually need to. If the code is not critical to performance, do not worry about it.

### 5.8 Using Barriers

The actual execution of collectives is not synchronised at all – except for MPI\_Barrier, that is. Up to three successive collectives on the same communicator can overlap – in theory, this allows for improved efficiency. Note that this is taking the global viewpoint; from the viewpoint of a single process, collectives are executed sequentially. Programmers do not notice this in practice, except that it makes it hard to measure times. To synchronise, call MPI\_Barrier; the first process leaves only after the last process enters, so all processes will run in lock-step.

Implementations usually tune for gang scheduling, and collectives often run faster when synchronised. Consider adding a barrier before every collective – it is an absolutely trivial change, after all. The best approach is to run 3–10 times with barriers, and 3–10 without; either one will be consistently faster than the other, or it will not matter which you choose. If you have major, non-systematic differences, then you have a nasty problem andmay need help from either or both of an MPI or operating tuning expert.

You can overlap collectives and point-to-point; MPI requires implementations to make that work, but it is strongly recommended to avoid doing that when performance is important. A correct program will definitely not hang or crash, but it may run horribly slowly. Remember that three collectives can overlap – point-to-point can interleave with those, and the scheduling can get very confused. It is much better to alternate the modes of use, and makes the program a lot easier to validate and debug, as well. For example: Start here ...

[ Consider calling MPI\_Barrier here ]

Any number of collective calls

```
[ Consider calling MPI_Barrier here ]
```

Any number of point-to-point calls, but remember to wait for **all** of those calls to finish.

And repeat from the beginning ...

# 5.9 In-Place Collectives

Passing the same array twice (for both the source and destination buffers) will **usually** work, but it is a breach of the Fortran standard, and is not clearly permitted in C (the standard can be read either way). If you are seriously masochistic, you can ask for the reasons offline, but I recommend not bothering; it is much better to avoid doing this if at all possible. It will rarely cause trouble or get diagnosed – but, if it does, the bug will be almost unfindable. There have been systems on which it would fail, for good reasons – the Hitachi SR2201 was one, for example.

MPI 2 defined a MPI\_IN\_PLACE pseudo-buffer, which specifies the result overwrites the input (i.e. the real buffer is both source and target). You should read the MPI standard for its full specification; it is probably most useful for MPI\_allgather[v], MPI\_alltoall[v] and MPI\_allreduce[v]. In those cases, you use it for the send buffer on all processes, and the send counts, datatype and offsets are ignored. Here is a C example; the Fortran is very similar.

## 5.10 Epilogue

That is essentially **all** you need to know about collectives! We have covered everything that seems to be used; MPI collectives look very complicated, but are really quite simple. There are a few more features, which are rarely used, and were mainly introduced by MPI 2 for advanced uses. They are mentioned in the extra lectures, but only in passing. There are two exercises on searching and scatterv.